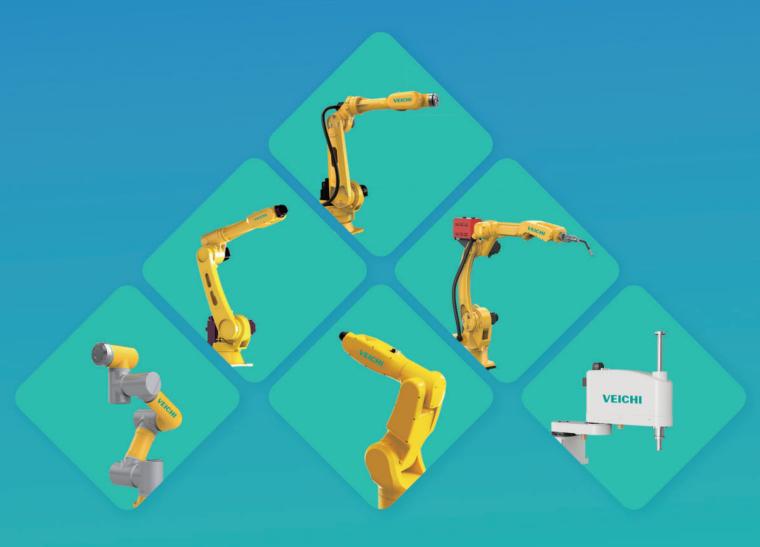
# **VEICHI**

# DRIVE FOR EVER



## **VEICHI**

### Suzhou Veichi Electric Co., Ltd

No.1000 Songjia Road, Guoxiang street, Wuzhong Economic and Technological Development Zone, Tel: +86-512-6617 1988 Fax: +86-512-6617 3610 Facebook: https://www.facebook.com/ veichigroup

WhatsApp: +86-138 2881 8903 Https://www.veichi.com



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VEICHI Electric (stock code: 688698) is a high-tech company focused on electrical drive and industrial control, offering a full range of industrial automation products. With facilities in Suzhou, Shenzhen, Xi'an, and a subsidiary in India, VEICHI serves customers worldwide with reliable and competitive offerings.

The company boasts an extensive portfolio of products, encompassing AC drives, servo systems, and control systems, which are widely utilized across various sectors such as heavy industry, light industry, and high-end equipment, providing scenario-based solutions that support the digital and intelligent transformation of the manufacturing industry. Moreover, the company is in lockstep with the zeitgeist, expanding its reach into burgeoning fields like robotics, renewable energy, and healthcare with a suite of innovative products, including hollow cup motors, frameless motors, hybrid inverters, and surgical power systems. These cutting-edge offerings significantly enhance the prosperity and advancement of the industries they serve.

On long-term and persistent independent R&D and innovation, VEICHI has successfully cultivated a series of patented technologies with independent intellectual property rights, and has mastered the core technologies of motor control such as vector control of PMSM, high-frequency pulse injection control, field-weakening control for higher speed, scalar WF control and vector control etc, and of silicon carbide application, motor parameter tuning and identification, motor control and protection, and motor speed tracking and start-up control. As of June 30, 2024, a total of 221 patents have been granted, including 51 patents for inventions.

VEICHI has been developing step by step over the past 19 years with abundant honorary awards and certificates from the state and competent authorities, including "the Third Batch of Special and Sophisticated 'Small Giant' Enterprises That Produce Novel and Unique Products" "High-tech Enterprises", "Jiangsu Provincial Engineering Technology Research Center", "Jiangsu Provincial Enterprise Technology Center", "Jiangsu Provincial Industrial Internet Development Demonstration Enterprise (Benchmarking Factory Category)" and others.

In the future, VEICHI Electric will continue to uphold the business philosophy of "guided by market demand and driven by technological innovation", strengthen the key core technology research and product iteration, and constantly expand its high-performance, high-quality, high-reliability applications, contributing to the development of electrical drive and industrial control with might and main.







### **Company Honors**





























- Suzhou VEICHI Phase II put into operation
- Suzhou VEICHI Phase III put into operation
- VEICHI medical subsidiary established

2023

**Company History** 

2005

- Beginning in Shenzhen
- First-generation of AC drives launched

2022 • Xi'an R&

- Xi'an R&D Center established
- VEICHI digital energy subsidiary established

2013

- Suzhou VEICHI Electric established
- First generation servo system launched



2021

- VEICHI subsidiary established
- Third batch of specialized, high-end and innovationdriven SMEs that provide distinctive products or services

2014

Suzhou VEICHI Phase I groundbreaking

2020

- SSE STAR Market landing Specialized, high-end and innovation-driven
- SMEs that provide distinctive products or services

2016

- Suzhou VEICHI Phase I project put into operation
- · First generation control system launched

2019

- Strategic restructure to a joint stock company VEICHI
- India subsidiary established

## The Robot Industry Experts

VEICHI gathers wisdom from three parties, actively leveraging their core technological advantages in the research and development and manufacturing of key components. With "robot joint modules" as their main business, we integrate resources from three parties to closely grasp customer needs, and develop more competitive robot joint module products to quickly capture market share and inject new momentum into the development of the robotics industry.

### **Talent**

Outstanding professional technical talents in the domestic industrial control field gather here. Currently, R&D personnel account for 37.16% of the total number of employees, and technical personnel with undergraduate degrees and above account for 74.62%.

#### technolog

As of June 30, 2024, a total of 221 patents, including 51 invention patents, mainly in the fields of electrical drive, industrial control, green energy, and industrial automation equipment are granted.

#### **R&D** Investment

**R&D Achievements** 

Veichi invests 10% of its operating income in R&D annually. It has established a 3-meter anechoic chamber, climate environment lab, temperature and vibration lab, full power range electric drive performance lab, and several industrial application platforms to enhance product performance, quality and reliability.

### **R&D Philosophy**

Abide by the R&D philosophy of "technological innovation for higher excellence", and customer needs, VEICHI serves with better products and technologies.

#### **Partners**

In-depth cooperative relationships with many famous domestic colleges and research institutions are set up, e.g. "Jiangsu Province Postdoctoral Innovation Practice Base" and "Jiangsu Province Graduate Student Workstation," continuously launching specialized product series with distinctive features.

#### **R&D Pattern**

EDA (Electronic Design Automation), which includes theoretical design, followed by simulation verification (thermal simulation, circuit simulation, code simulation), and then prototype testing, and IPD (Integrated Product Development), which features efficiency and collaboration are adopted.

Selection Table						Page01-04
1. Scara Robots						Page05-12
VCG030-500	05			VCG100-700		06
VCH030-Optional Length	07			VCH100-Optio	nal Length	08
VCH200-1000	09			VCH500-1200		10
VCW030-Optional Length	11			VCW060-Optio	onal Length	12
2. Collaborative Robots						Page13-17
VC-TCR030	13	VC-TCR0	50	14	VC-TCR100	15
VC-TCR200	16	VC-TCR3	000	17		
3. Vertical Polyarticulated R	obots					Page18-37
■ Welding Robots						Page24-26
VC-TKB1400	24			VC-TKB1440		25
VC-TKB2030	26					
■ General Robots 6-axis					Page18-23	3、Page27-34
VC-TKB1010	18	VC-TRB0	50	19	VC-TKB060	20
VC-TKB070	21	VC-TKB1	210	22	VC-TKB1100	23
VC-TKB1600	27	VC-TKB2	2670	28	VC-TKB2690	28
VC-TKB3670	29	VC-TKB3	3690	30	VC-TKB5600	31
VC-TKB5700	31	VC-TKB5	800	32	VC-RRB6700	33
VC-RRB6600	34					
■ General Robots 4-axis						Page35-37
VC-TKB460	35	VC-TKB4	4600	36	VC-TKB660	37
4. Accessory		,,,,,,				Page38-43
VC-TRP04 Pendant	38		İ	VC-TRC4-A03	Controller	39
VC-TRC5-B06 Controller	40			VC-TRC5-G06		41
VC-TRC3-C06 Controller	42			VC-TRC3-D06		43
5. Application Scenario	74			VC 11C3-D00	CONTROLLE	Page44-49
6. Partner						Page50
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## Quick Selection Table

## Quick Selection Table

Product			VEICHI	VEICHI	VEICHI	
Mode	el	VCG030-500	VCG100-700	VCH030-Optional Length	VCH100-Optional Length	
Paylo	ad	3kg	10kg	3kg	10kg	
Beam Lengt		500mm	700mm	400/500/600mm	800/900/1000mm	
Prote		IP40	IP40	IP40	IP40	
Mome of Ine		0.05kg*m²	0.3kg*m²	0.05kg*m²	0.3kg*m²	
	J1/J2	±0.01mm	±0.02mm	±0.01mm	±0.02mm	
Position Repeat	J3	±0.01mm	±0.01mm	±0.01mm	±0.01mm	
Accuracy	J4	±0.01°	±0.01°	±0.01°	±0.01°	

Prod	roduct		VEICHI	VEICHI	VEICHI
Mod	el	VCH200-1000	VCH500-1200	VCW030-Optional Length	VCW060-Optional Length
Paylo	oad	20kg	50kg	3kg	6kg
Bear Leng		1200mm	1200mm	500/600mm	500/600/700mm
Prot	ection el	IP40	IP40	IP40	IP40
Mon of In		2.45kg*m²	4.35kg*m²	0.05kg*m²	0.05kg*m²
	J1/J2 ±0.05mm ±0.05mm		±0.05mm	±0.01mm	±0.02mm
Repeat			±0.02mm	±0.01mm	±0.01mm
J4 ±0.005° ±0.005		±0.005°	±0.01°	±0.01°	

Product					
Model	VC-TCR030	VC-TCR050	VC-TCR100	VC-TCR200	VC-TCR300
Payload	3kg	5kg	10kg	20kg	30kg
Beam Length	585mm	900mm	1310mm	1650mm	1800mm
Protection Level	IP54/IP67	IP54/IP67	IP54/IP67	IP54	IP54
Position Repeat Accuracy	±0.03mm	±0.03mm	±0.05mm	±0.1mm	±0.1mm

## Quick Selection Table

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Quic	N JU	lection <sup>*</sup>	Iabi	C

Product	To the second se	Mode	TO THE STATE OF TH	Youn	Mich
Model	VC-TKB1010	VC-TRB050	VC-TKB060	VC-TKB070	VC-TKB1210
Payload	1kg	3kg	6kg	7kg	7kg
Beam Length	370mm	616mm	720mm	910mm	960mm
Protection Level	IP54	IP54	IP54/IP67 (5.6 axis optional)	IP54/IP67	IP54/IP67 (5.6 axis optional)
Position Repeat Accuracy	±0.01mm	±0.02mm	±0.02mm	±0.02mm	±0.04mm

Product	VECCH				Man .
Model	VC-TKB1100	VC-TKB1400	VC-TKB1440	VC-TKB2030	VC-TKB1600
Payload	10kg	6kg	10kg	6kg	12kg
Beam Length	1110mm	1412mm	1455mm	2078mm	1410mm
Protection Level	IP54	IP54/IP67 (5.6 axis optional)	IP54	IP54	IP54/IP67 (5.6 axis optional)
Position Repeat Accuracy	±0.03mm	±0.05mm	±0.05mm	±0.07mm	±0.06mm

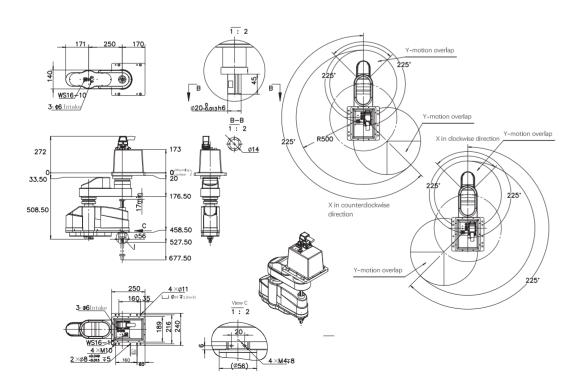
Product					
Model	VC-TKB2670/2690	VC-TKB3670	VC-TKB3690	VC-TKB5600/5700	VC-TKB5800
Payload	20kg	30kg	30kg	60/70kg	50kg
Beam Length	1721/1920mm	1721mm	1920mm	2119mm	2448mm
Protection Level	IP54/IP67 (5.6 axis optional)	IP54/IP67 (5.6 axis optional)	IP54/IP67 (5.6 axis optional)	IP54	IP54
Position Repeat Accuracy	±0.05mm	±0.05mm	±0.05mm	±0.08mm	±0.08mm

Product					
Model	VC-RRB6700	VC-RRB6600	VC-TKB460	VC-TKB4600	VC-TKB660
Payload	210kg	155kg	30kg	12kg	180kg
Beam Length	2700mm	3200mm	1840mm	1435mm	3200mm
Protection Level	IP54/IP65 (5.6 axis optional)	IP54/IP65 (5.6 axis optional)	IP54	IP54	IP54/IP65 (4 axis optional)
Position Repeat Accuracy	±0.1mm	±0.1mm	±0.08mm	±0.08mm	±0.1mm

# VCG030-500 Payload: 3kg Length: 500mm



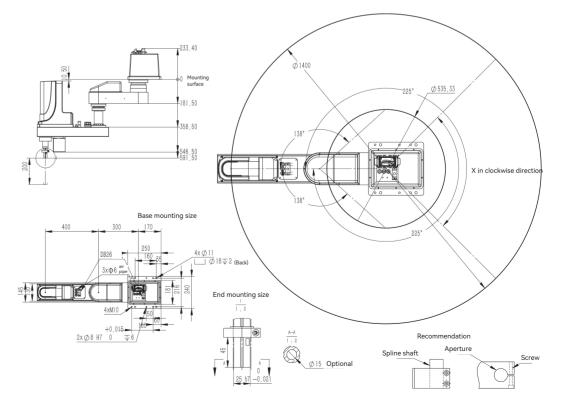
			J1	J2	J3	R
	Leng	th(mm)	250	250	150	-
Specification	5	D (0)	225	225		360
	Rotation	Range (°)	-225	-225	-	-360
	Re	ducer	Harmonic drive	Harmonic drive	-	-
Reducer Mechanism	Caralinatinita	Motors-Reducer	Synchronous	s belt pulley	Synchronous belt pulley	Synchronous belt pulley
	Conductivity	Reducers-Output	Direct conne	ection	/	/
Position Rep	peat Accuracy(XYZ	:: mm)(r:°)	±0.	.01	±0.01	±0.01
Max Sp	eed (XYZ:mm/sec)	(r: °/s)	9420 1000		1000	3500
	Rated Load(kg)		3kg			
Standard cycle	e time: 1kg Handlir	ng Time (sec)	0.32			
R-axis M	Ioment of Lnertia	(kgm2)	0.05			
	I/O		0.2*10			
User Pipe (inside)		Ф6*3				
Robotics Cable Length (m)		Standard: 3 Optional: 5				
Body Weight(kg)			27	'kg		
Controller		VC-TRC4-A03				
Operating Temperature			0-4	45°C		







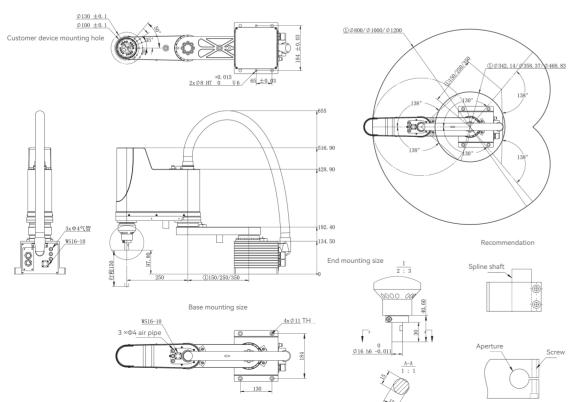
			J1 轴	J2 轴	J3 轴	R 轴	
	Length(mm)		300	400	200	-	
Specification	Potation	n Range (°)	225	138		360	
	Kotatioi	r Karige ( )	-225	-138	-	-360	
	Re	ducer	Harmonic drive	Harmonic drive	-	Synchronous belt pulley	
Reducer Mechanism	C = == al == ±1: . : ±= .	Motors-Reducer	Synchronous	s belt pulley	-		
	Conductivity	Reducers-Output		Direct co	nnection		
Position Re	peat Accuracy(XY	Z: mm)(r:°)	±0	.02	±0.01	±0.01	
Max Sp	peed (XYZ:mm/sec	)(r: °/s)	13816 1000		1000	720	
	Rated Load(kg)		10kg				
Standard Cyc	cle Time: 1kg Hand	ling Time (sec)	0.6				
R-axis N	Moment of Lnertia	(kgm2)	0.3				
	I/O		0.2*20				
	User Pipe (inside)		Ф6*3				
Robotics Cable Length (m)		标准: 3 选配: 5					
Body Weight(kg)			43	lkg			
Controller			VC-TR	C4-A03			
Operating Temperature			0-4	i5℃			



# VCH030-Beam Length Payload: 3kg Length: 400/500/600mm



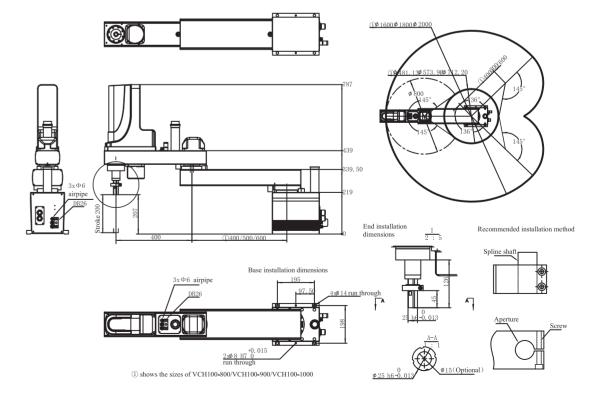
			J1		J2	J3	R	
	Length(mm)	VCH030-400	VCH030-500	VCH030-600	250	150		
C:::::	Length(mm)	150	250	350	230	150	-	
Specification	Rotation Range (°)		130		138		360	
	Rotation Range ( )		-130		-138	_	-360	
Reducer	Reducer		Harmonic dr	rive	Harmonic drive	-	Harmonic drive	
Mechanism	Conductivity	Motors-Reduc	cer Direct co	onnection		-	Synchronous	
	Conductivity	Reducers-Out	put	Direct cor	nnection		belt pulley	
Position Repea	at Accuracy(XYZ: mm)(r:°)%	±0.01				±0.01	±0.01	
Max Spee	d (XYZ:mm/sec)(r: °/s)	6280/7065/7850				1000	720	
R	ated Load(kg)	3kg						
Standard Cycle	Time: 1kg Handling Time (sec)			0.4				
R-axis Mo	ment of Inertia(kgm2)			0.05				
	1/0	0.2*10						
Use	er Pipe (inside)	Ф4*3						
Robotics Cable Length (m)		Standard: 3 Optional: 5						
Во	dy Weight(kg)	16.8/17.9/19		9kg				
	Controller	VC-TRC4-A03						
Opera	ting Temperature			0-45°C	0-45℃			





# VCH100-Beam Length Payload: 10kg Length: 800/900/1000mm

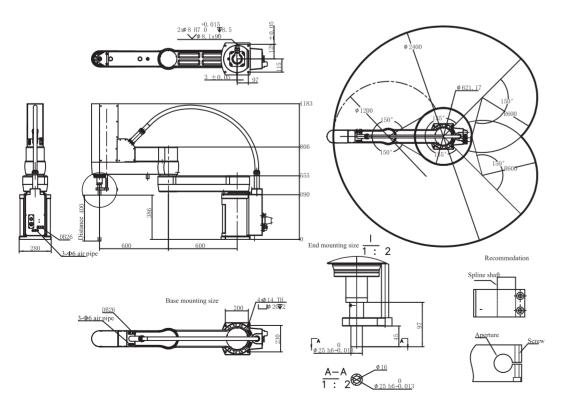
			J1		J2	J3	R
	Length(mm)	VCH100-800	VCH100-900	VCH100-1000	400	200	
Specification		400	500	600	400	200	_
Specification	Rotation Range (°)		136		145	_	360
	Notation Nange ( )		-136		-145		-360
Reducer	Reducer		Harmonic drive		Harmonic drive	-	Harmonic drive
Mechanism	Motors-Reducer		Direct con	nection		-	Synchronous
	Reducers-Output		Direct connect				belt pulley
Position Repeat Accuracy(XYZ: mm)(r:°)% ±0.02		)2		±0.01	±0.01		
Max Spee	ed (XYZ:mm/sec)(r: °/s)	11304/12089/12874			1000	720	
F	Rated Load(kg)			10kg			
Standard Cycle	Time: 1kg Handling Time (sec)			0.6			
R-axis Mo	oment of Inertia(kgm2)			0.3			
	I/O			0.2*20			
Us	User Pipe (inside)		Ф6*3				
Roboti	cs Cable Length (m)	Standard: 3 Opt			tional: 5		
Во	ody Weight(kg)	46kg	48kg	50kg			
	Controller	Controller VC-TRC4-A0			<b>1</b> 03		
Opera	ating Temperature			0-45°C			



# VCH200-1000 Payload: 20kg Length: 1200mm



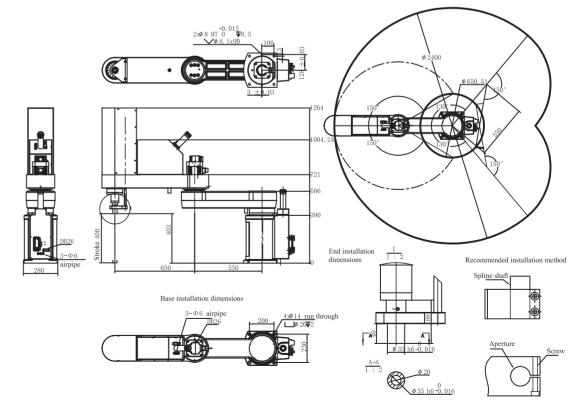
			J1	J2	J3	R	
	Lengt	:h(mm)	600	600	400	-	
Specification	Datation	Danasa (°)	135	150		180	
	Rotation	Range (°)	-135	-150	-	-180	
	Red	lucer	RV	RV	Ball screw	Harmonic drive	
Reducer Mechanism	Conductivity	Motors-Reducer	Direct co	onnection	Synchronou	s belt pulley	
riceriamsm	Conductivity	Reducers-Output		Direct co			
Position Re	peat Accuracy(XYZ	7: mm)(r:°) ※	±0	±0.05 ±0.02		±0.005	
Max Spe	eed (XYZ:mm/sec)	)(r: °/s)	12417 1000 7			720	
	Rated Load(kg)		20kg				
Standard Cyc	cle Time: 1kg Handli	ng Time (sec)	0.91				
R-axis N	Noment of Inertia(	(kgm2)	2.45				
	I/O			0.2	*20		
User Pipe (inside)				Фб	5*3		
Robotics Cable Length (m)		Standard: 3 Optional: 5					
Body Weight(kg)				155	ōkg		
	Controller		VC-TRC4-A03				
Оре	erating Temperatu	ire		0-4	.5°C		







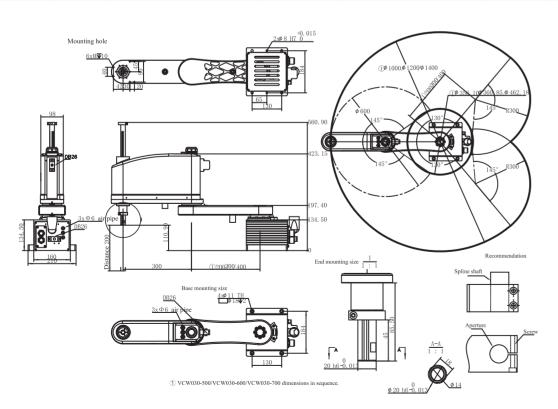
			J1	J2	J3	R	
	Lengt	h(mm)	550	650	400	-	
Specification	Detetion	Danga (°)	130	150		180	
	Rotation		-130	-150	-	-180	
	Red	ucer	RV RV		Ball screw	Harmonic drive	
Reducer Mechanism	Conductivity	Motors-Reducer	Direct co	onnection	Synchronou	is belt pulley	
	conductivity	Reducers-Output		Direct co	nnection		
Position Rep	peat Accuracy(XYZ	/: mm)(r:°)	±0.05		±0.02	±0.005	
Max Spe	Max Speed (XYZ:mm/sec)(r: °/s)		10162 1000		720		
	Rated Load(kg)			50	50kg		
Standard Cyc	de Time: 1kg Handli	ng Time (sec)	0.98				
R-axis M	noment of Inertial	kgm2)					
	I/O			0.2	*20		
l	Jser Pipe (inside)		Ф6*3				
Robo	tics Cable Length	(m)	Standard: 3 Optional: 5				
E	Body Weight(kg)		170kg				
	Controller			VC-TR	C4-A06		
Ope	erating Temperatu	ire		0-4	45°C		



# VCW030- Beam Length Payload: 3kg Length: 500/600mm



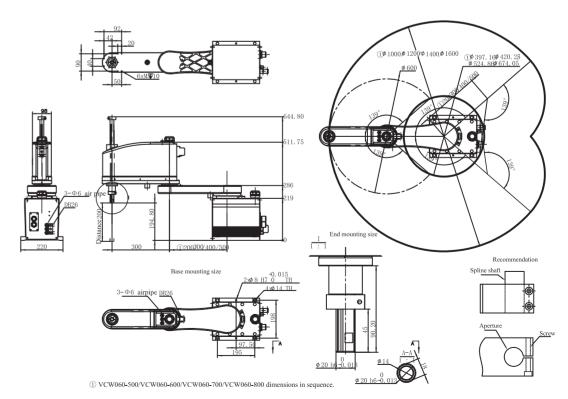
			J1	J2	J3	R
	Length(mm)	VCW030-500	VCW030-600	300	200	
Consideration	Length(mm)	200	300	300	200	
Specification	Rotation Range (°)		130	145	_	360
	Notation Nange ( )		-130			-360
Reducer	Reducer	На	armonic drive	Harmonic drive	-	Harmonic drive
Mechanism	Conductivity	Motors-Reducer	Direct connection		-	Synchronous
	conductivity	Reducers-Output	Direct co	onnection		belt pulley
Position Repea	at Accuracy(XYZ: mm)(r:°)%	YZ: mm)(r:°)** ±0.01			±0.01	±0.01
Max Spee	d (XYZ:mm/sec)(r: °/s)	7693/8478				3500
R	ated Load(kg)		3kg			
Standard Cycle	Time: 1kg Handling Time (sec)		0.4			
R-axis Mo	ment of Inertia(kgm2)		0.05			
	I/O		0.2*10	)		
Us	er Pipe (inside)					
Robotio	cs Cable Length (m)	Standard: 3 Option		otional: 5		
Во	dy Weight(kg)		g			
	Controller		VC-TRC4-	-A03		
Opera	iting Temperature		0-45°0			





# VCW060- Beam Length Payload: 6kg Length: 500/600/700mm

			J1		J2	J3	R
	Length(mm)	VCW060-500	VCW060-600	VCW060-700	300	200	
C::::+:	Lengui(iiii)	200	300	400	300	200	-
Specification	Rotation Range (°)		139		139	_	360
	Notation Nange ( )		-139		-139		-360
Reducer	Reducer		Harmonic dr	ive	Harmonic drive	-	Harmonic drive
Mechanism	Conductivity	Motors-Reduc	er Direct co	onnection		-	Synchronous
	conductivity	Reducers-Out	put	Direct con	nection		belt pulley
Position Repe	at Accuracy(XYZ: mm)(r:°)::		±0.0	2		±0.01	±0.01
Max Spee	d (XYZ:mm/sec)(r: °/s)		7693/847	8/9263		1000	3500
R	ated Load(kg)			6kg			
Standard Cycle	Time: 1kg Handling Time (sec)			0.4			
R-axis Mo	ment of Inertia(kgm2)			0.05			
	I/O			0.2*10			
Us	er Pipe (inside)			Ф6*3			
Robotio	cs Cable Length (m)			Standard: 3 Opt	ional: 5		
Во	ody Weight(kg)			37.5/40/42	kg		
	Controller			VC-TRC4-A	<b>1</b> 03		
Opera	ating Temperature			0-45°C			

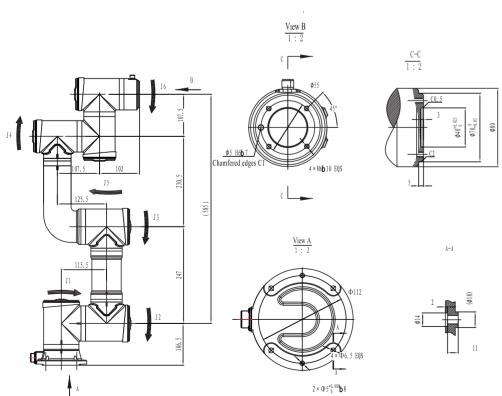


# VC-TCR030 Payload: 3kg Length: 585mm



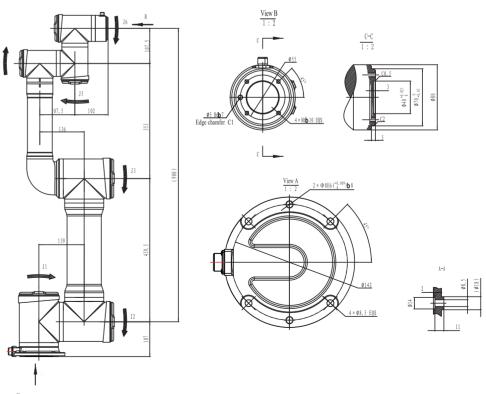
Model	VC-1	TCR030		
Payload	3kg			
Max Working Radius	58	5mm		
Body Weight	1	6kg		
Rated Power	0.	9kw		
	J1	180°/s		
	J2	180°/s		
May Cross d	J3	180°/s		
Max Speed	J4	180°/s		
	J5	180°/s		
	J6	180°/s		
	J1	±175°		
	J2	±175°		
Mary On anation Assa	J3	-240° ~ +60°		
Max Operation Area	J4	±175°		
	J5	±175°		
	J6	±360°		
Protective Level	IP54/IP67			
Position Repeat Accuracy X	±0.0	±0.03mm		
Working Temperature	0~	0~45°C		
Controller	VC-TF	RC5-G06		





Madal	V/C 7	CDOEO		
Model		VC-TCR050		
Payload		skg		
Max Working Radius	90	0mm		
Body Weight	2	6kg		
Rated Power	2.5	55kw		
	J1	180°/s		
	J2	180°/s		
Max Speed	J3	180°/s		
	J4	180°/s		
	J5	180°/s		
	J6	180°/s		
	J1	±175°		
	J2	±175°		
	J3	-245° ~ +65°		
Max Operation Area	J4	±175°		
	J5	±175°		
	J6	±360°		
Protective Level	IP54	IP54/IP67		
Position Repeat Accuracy *	±0.0	±0.03mm		
Working Temperature	0~	0~45°C		
Controller	VC-TF	RC5-G06		

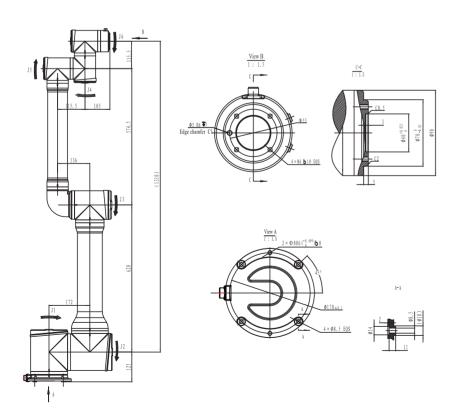




# VC-TCR100 Payload: 10kg Length: 1310mm

Model	VC-1	VC-TCR100			
Payload	1	0kg			
Max Working Radius	131	10mm			
Body Weight	4	3kg			
Rated Power	3.	5kw			
	J1	120°/s			
	J2	120°/s			
May Canad	J3	120°/s			
Max Speed	J4	180°/s			
	J5	180°/s			
	J6	180°/s			
	J1	±175°			
	J2	±175°			
Mary Orangelian Assa	J3	-245° ~ +65°			
Max Operation Area	1/4	+175°			





J5

IP54/IP67

±0.05mm

0~45°C VC-TRC5-G06

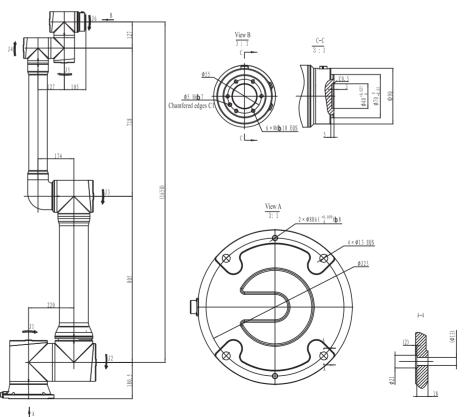
±175°

±175° ±360°



Model	VC-	VC-TCR200		
Payload	:	20kg		
Max Working Radius	16	50mm		
Body Weight		68kg		
Rated Power	3	3.9kw		
	J1	100°/s		
	J2	100°/s		
Max Speed	J3	150°/s		
	J4	180°/s		
	J5	180°/s		
	J6	180°/s		
	J1	±175°		
	J2	±175°		
Mana On and the Area	J3	-245° ~ +65°		
Max Operation Area	J4	±175°		
	J5	±175°		
	J6	±360°		
Protective Level		IP54		
Position Repeat Accuracy X	±(	±0.1mm		
Working Temperature	0	0~45°C		
Controller	VC-T	RC5-G06		





Protective Level

Controller

Position Repeat Accuracy \*

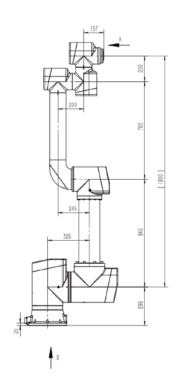
Working Temperature

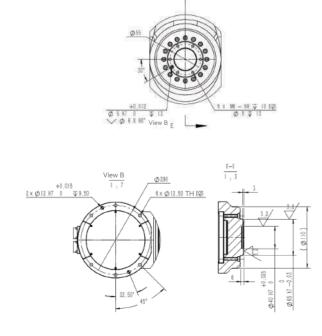
# VC-TCR300 Payload: 30kg Length: 1800mm

VC-TKB101  Payload: 11  Length: 370m	κg
--------------------------------------	----

Model	VC-TCR300		
Payload	30kg		
Max Working Radius	180	0mm	
Body Weight	15	4kg	
Rated Power	5.9	5kw	
	J1	100°/s	
	J2	100°/s	
Max Speed	J3	150°/s	
	J4	180°/s	
	J5	180°/s	
	J6	180°/s	
	J1	±175°	
	J2	±175°	
May Operation Area	J3	-245° ~ +65°	
Max Operation Area	J4	±175°	
	J5	±175°	
	J6	±360°	
Protective Level	IP54		
Position Repeat Accuracy X	±0.1mm		
Working Temperature	0~45°C		
Controller	VC-TR	C5-B06	



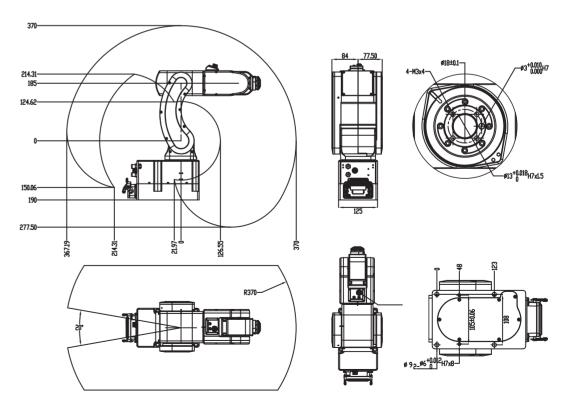




View A

Model	VC-TKB1010		
Payload	1kg		
Max Working Radius	37	0mm	
DOF	6-	-axis	
Body Weight	1	5kg	
Rated Power	0.	4kw	
	J1	320°/s	
	J2	320°/s	
Max Speed	J3	375°/s	
	J4	500°/s	
	J5	470°/s	
	J6 500°/s		
	J1	±170°	
	J2	-80° ~ 120°	
May Operation Area	J3	-180° ~ 50°	
Max Operation Area	J4	±170°	
	J5	±125°	
	J6	±360°	
Protective Level	IP54		
Position Repeat Accuracy **	±0.01mm		
Controller	VC-TRC4-A03		
Working Temperature	0~45°C		



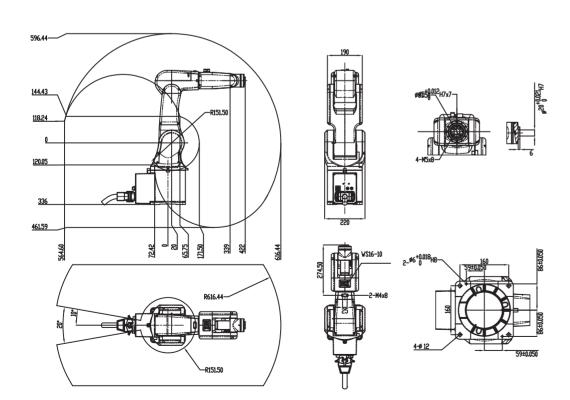


# VC-TRB050 Payload: 3kg Length: 616mm



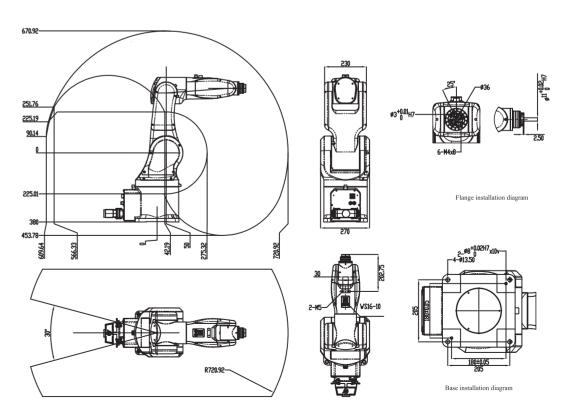
Model	VC-TRB050		
Payload	3kg		
Max Working Radius	616mm		
DOF	6-8	axis	
Body Weight	35kg		
Rated Power	1.05kw		
	J1	450°/s	
	J2	450°/s	
May Spand	J3	720°/s	
Max Speed	J4	720°/s	
	J5	720°/s	
	J6	720°/s	
	J1	±170°	
	J2	-80° ~ 120°	
May Operation Area	J3	-75° ~ 75°	
Max Operation Area	J4	±120°	
	J5	±120°	
	J6	±360°	
Protective Level	IP54		
Position Repeat Accuracy ※	±0.02mm		
Controller	VC-TRC4-A03		
Working Temperature	0~45°C		





Model	VC-TKB060	
Payload	6kg	
Max Working Radius	720	mm
DOF	6-8	axis
Body Weight	40	kg
Rated Power	2.2	!kw
	J1	450°/s
	J2	450°/s
Man Crand	J3	450°/s
Max Speed	J4	458°/s
	J5	540°/s
	J6	360°/s
	J1	±165°
	J2	-75° ~ 110°
Man On austing Aug	J3	-100° ~ 55°
Max Operation Area	J4	±160°
	J5	±110°
	J6	±360°
Protective Level	IP54/IP67(5/6-axis optional)	
Position Repeat Accuracy X	±0.02mm	
Controller	VC-TRC4-A03	
Working Temperature	0~45°C	



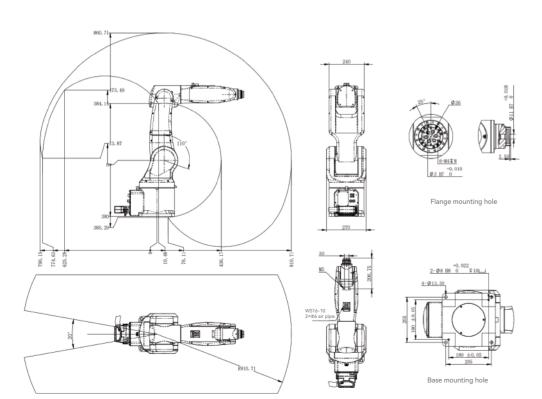


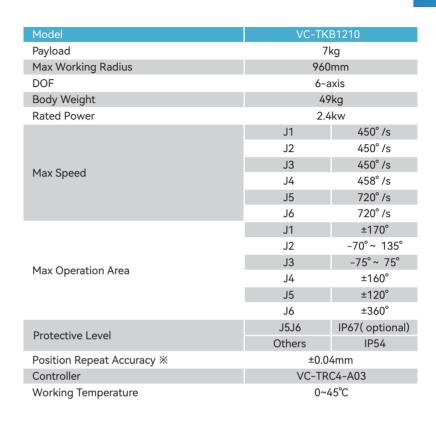




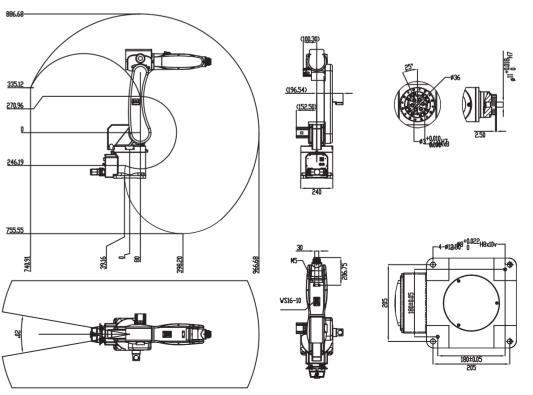
Model	VC-TKB070	
Payload	7kg	
Max Working Radius	910mm	
DOF	6-8	axis
Body Weight	50	kg
Rated Power	2.4kw	
	J1	450°/s
	J2	450°/s
May Canad	J3	450°/s
Max Speed	J4	458°/s
	J5	720°/s
	J6	720°/s
	J1	±170°
	J2	-75° ~ 110°
May Operation Area	J3	-120° ~ 50°
Max Operation Area	J4	±160°
	J5	±120°
	J6	±360°
Protective Level	IP54/IP67	
Position Repeat Accuracy*	±0.02mm	
Controller	VC-TRC4-A03	
Working Temperature	0~45°C	









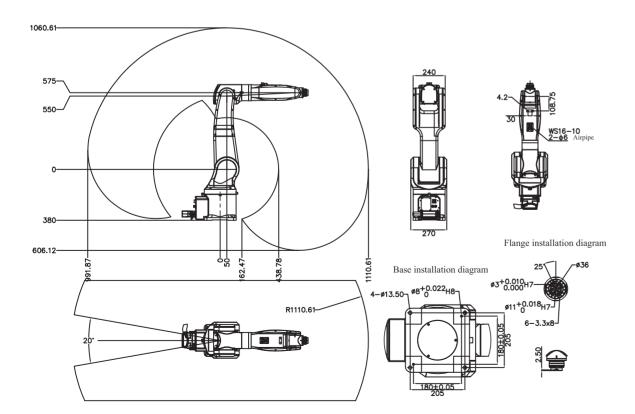


# VC-TKB1100 Payload: 10kg Length: 1110mm



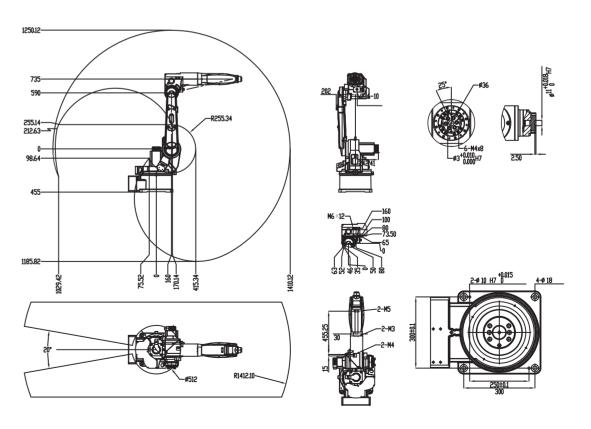
Model	VC-TKB1100	
Payload	10kg	
Max Working Radius	1110mm	
DOF	6-8	axis
Body Weight	55kg	
Rated Power	2.5kw	
	J1	360°/s
	J2	300°/s
Max Speed	J3	300°/s
Max Speed	J4	520°/s
	J5	360°/s
	J6	450°/s
	J1	±170°
	J2	-75° ~ 110°
May Operation Area	J3	-120° ~ 50°
Max Operation Area	J4	±160°
	J5	±120°
	J6	±360°
Protection Level	IP54	
Position Repeat Accuracy **	±0.03mm	
Controller	VC-TRC4-A03	
Working Temperature	0~45°C	





Model	VC-T	KB1400	
Payload		6kg	
Max Working Radius	14	1412mm	
DOF	6-	axis	
Body Weight	1	160kg	
Rated Power	3	3.5kw	
	J1	198° /s	
	J2	198°/s	
Max Speed	J3	169°/s	
Max Speed	J4	360°/s	
	J5	360°/s	
	J6	600°/s	
	J1	±170°	
	J2	-92° ~ 153°	
Max Operation Area	J3	-100° ~ 80°	
Max Operation Area	J4	±140°	
	J5	±120°	
	J6	±360°	
Protection Level	IP54/IP67(5/	IP54/IP67(5/6-axis optional)	
Position Repeat Accuracy X	±0.	±0.05mm	
Controller	VC-T	VC-TRC5-B06	
Working Temperature	0-	0~45°C	



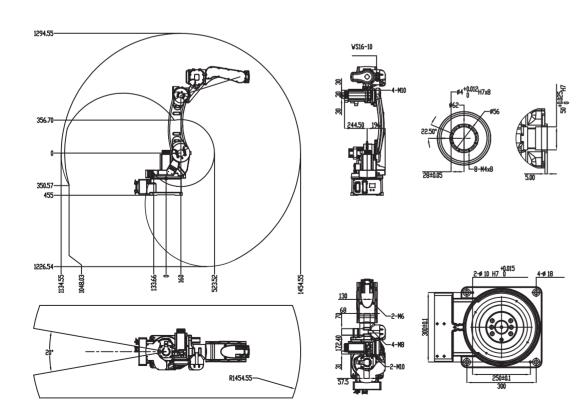


### VC-TKB1440 Payload: 10kg Length: 1455mm

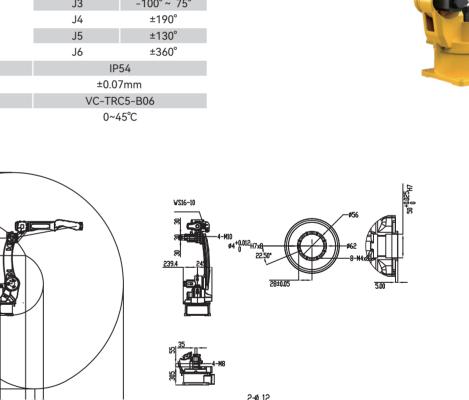


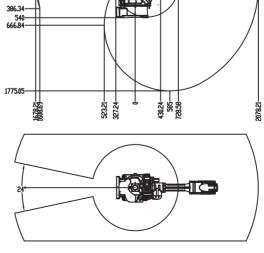
Model	VC-TK	(B1440
Payload	10kg	
Max Working Radius	145	5mm
DOF	6-8	axis
Body Weight	15	5kg
Rated Power	4.3kw	
	J1	198°/s
	J2	198°/s
May Speed	J3	210°/s
Max Speed	J4	330°/s
	J5	450°/s
	J6	700°/s
	J1	±170°
	J2	-92° ~ 153°
May Operation Area	J3	-100° ~ 75°
Max Operation Area	J4	±190°
	J5	±130°
	J6	±360°
Protection Level	IP54	
Position Repeat Accuracy X	±0.05mm	
Controller	VC-TRC5-B06	
Working Temperature	0~45°C	





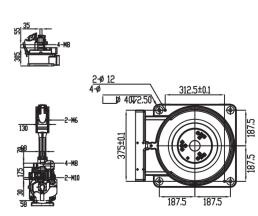
Model	VC-TKB2030		
Payload	6	6kg	
Max Working Radius	207	78mm	
DOF	6-	axis	
Body Weight	21	10kg	
Rated Power	4.	3kw	
	J1	168°/s	
	J2	148°/s	
May Casad	J3	160°/s	
Max Speed	J4	330°/s	
	J5	450°/s	
	J6	700°/s	
	J1	±160°	
	J2	-90° ~ 150°	
May Operation Area	J3	-100° ~ 75°	
Max Operation Area	J4	±190°	
	J5	±130°	
	J6	±360°	
Protection Level	IP54		
Position Repeat Accuracy※	±0.07mm		
Controller	VC-TRC5-B06		
Working Temperature	0~45°C		





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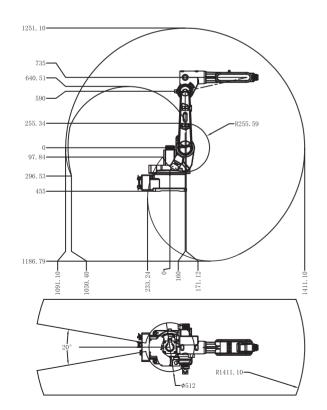


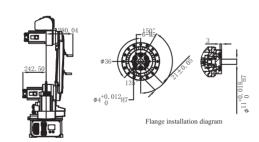
## VC-TKB1600 Payload: 12kg Length: 1410mm

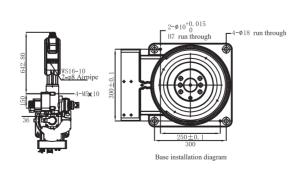
VC-TKB2670	
Payload: 20kg Length: 1721mm	

Model	VC-TKB1600	
Payload	12kg	
Max Working Radius	1410mm	
DOF	6-8	axis
Body Weight	160kg	
Rated Power	4.3kw	
	J1	148°/s
	J2	148°/s
May Spand	J3	230°/s
Max Speed	J4	480°/s
	J5	256°/s
	J6	450°/s
	J1	±170°
	J2	-92° ~ 153°
Max Operation Area	J3	-100° ~ 80°
Max Operation Area	J4	±140°
	J5	±120°
	J6	±360°
Protection Level	IP54/IP67(5/6-axis optional)	
Position Repeat Accuracy*	±0.06mm	
Controller	VC-TRC5-B06	
Working Temperature	0~45°C	



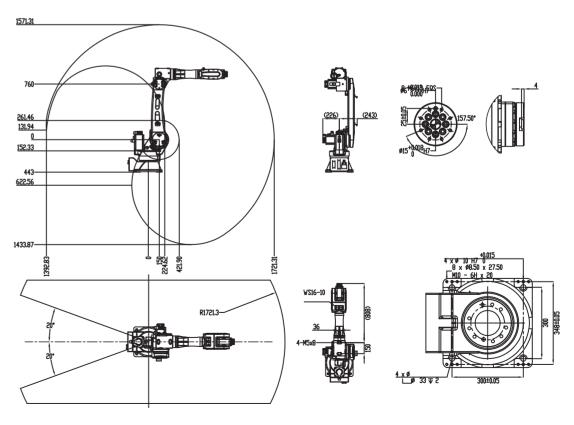






Model	VC-T	KB2670	
Payload	2	20kg	
Max Working Radius	172	1721mm	
DOF	6-	6-axis	
Body Weight	21	210kg	
Rated Power	4.	4.5kw	
	J1	186°/s	
	J2	186°/s	
May Chand	J3	200°/s	
Max Speed	J4	452°/s	
	J5	400°/s	
	J6	555°/s	
	J1	±160°	
	J2	-80° ~ 150°	
May Operation Area	J3	-100° ~ 80°	
Max Operation Area	J4	±150°	
	J5	±110°	
	J6	±360°	
Protection Level	IP54/IP67(5/6	IP54/IP67(5/6-axis optional)	
Position Repeat Accuracy **	±0.	±0.05mm	
Controller	VC-TF	VC-TRC5-B06	
Working Temperature	0~	0~45°C	



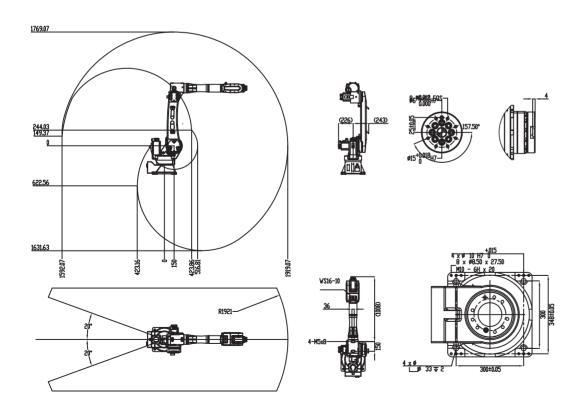


# VC-TKB2690

Payload: 20kg ength: 1920mm

Model	VC-TKB2690	
Payload	20kg	
Max Working Radius	1920mm	
DOF	6-axis	
Body Weight	220kg	
Rated Power	4.7kw	
	J1	186°/s
	J2	186°/s
Max Speed	J3	200°/s
Max Speed	J4	452°/s
	J5	400°/s
	J6	555°/s
	J1	±160°
	J2	-80° ~ 150°
May Operation Area	J3	-100° ~ 80°
Max Operation Area	J4	±150°
	J5	±110°
	J6	±360°
Protective Level	IP54/IP67(5/6-axis optional)	
Position Repeat Accuracy ※	±0.05mm	
Controller	VC-TRC5-B06	
Working Temperature	0~45°C	

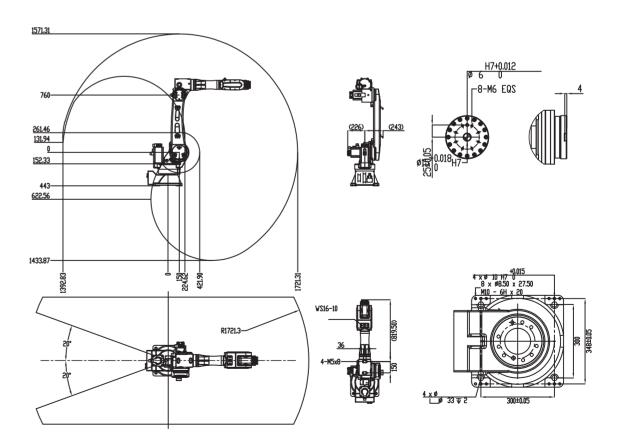






Model	VC-TK	B3670	
Payload	30kg		
Max Working Radius	1721mm		
DOF	6-axis		
Body Weight	220	220kg	
Rated Power	51	(W	
	J1	186°/s	
	J2	170°/s	
Max Speed	J3	200°/s	
Max Speed	J4	452°/s	
	J5	330°/s	
	J6	450°/s	
	J1	±160°	
	J2	-80° ~ 150°	
May Operation Area	J3	-100° ~ 80°	
Max Operation Area	J4	±150°	
	J5	±110°	
	J6	±360°	
Protective Level	IP54/IP67(5/6-axis optional)		
Position Repeat Accuracy X	±0.05mm		
Controller	VC-TRC5-B06		
Working Temperature	0~45°C		





# VC-TKB3690 Payload: 30kg Length: 1920mm

VC-TKB5600
Payload: 60kg
Length: 2119mm

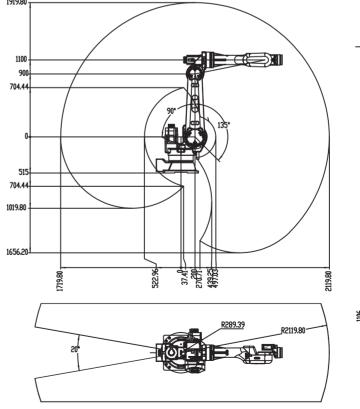
Model	VC-T	VC-TKB3690	
Payload	3	30kg	
Max Working Radius	192	1920mm	
DOF	6-	axis	
Body Weight	22	20kg	
Rated Power	5.	2kw	
	J1	186°/s	
	J2	170°/s	
May Spand	J3	200°/s	
Max Speed	J4	452°/s	
	J5	330°/s	
	J6	450°/s	
	J1	±160°	
	J2	-80° ~150°	
Man On anation Anna	J3	-100° ~80°	
Max Operation Area	J4	±150°	
	J5	±110°	
	J6	±360°	
Protective Level	IP54/IP67(5/6	-axis optional)	
Position Repeat Accuracy X	±0.0	)5mm	
Controller	VC-TI	RC5-B06	
Working Temperature	Working Temperature 0~45°C		

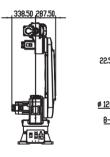


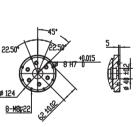
1769.07	H7+.012
244.03 149.33 0	8-M6 EQS (243) (243) (243) (243) (243) (243)
622.56 1631.63 163.63 163.63 163.63 163.63 163.63 163.63 163.63	8 × #8.50 × 27.50 MIO - 6H × 20
20°	4-H5x8 33 ₹ 2 300±0,05

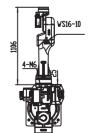
Model	VC-T	KB5600	
Payload	6	60kg	
Max Working Radius	211	2119mm	
DOF	6-	6-axis	
Body Weight	60	600kg	
Rated Power	6.	6.5kw	
	J1	127°/s	
	J2	105°/s	
May Spand	J3	165°/s	
Max Speed	J4	253°/s	
	J5	250°/s	
	J6	372°/s	
	J1	±170°	
	J2	-90° ~ 135°	
May Operation Area	J3	-185° ~ 90°	
Max Operation Area	J4	±200°	
	J5	±105°	
	J6	±360°	
Protective Level	II	IP54	
Position Repeat Accuracy **	±0.0	08mm	
Controller	VC-TF	RC3-C06	
Working Temperature	0~	0~45°C	

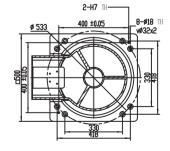








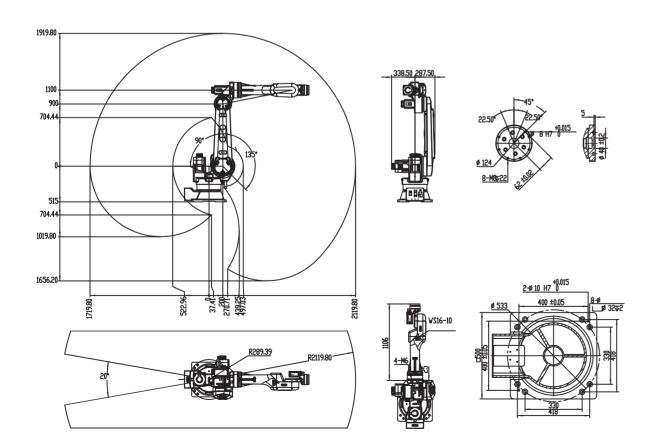




# VC-TKB5700 Payload: 70kg Length: 2119mm

Model	VC-TKB5700	
Payload	70kg	
Max Working Radius	2119mm	
DOF	6-axis	
Body Weight	600kg	
Rated Power	6.8kw	
	J1	127°/s
	J2	105°/s
May Coand	J3	165°/s
Max Speed	J4	253°/s
	J5	250°/s
	J6	372°/s
	J1	±170°
	J2	-90° ~ 135°
May Operation Area	J3	-185° ~ 90°
Max Operation Area	J4	±200°
	J5	±105°
	J6	±360°
Protective Level	IP54	
Position Repeat Accuracy X	±0.0	)8mm
Controller	VC-TR	C3-C06
Working Temperature	0~45°C	

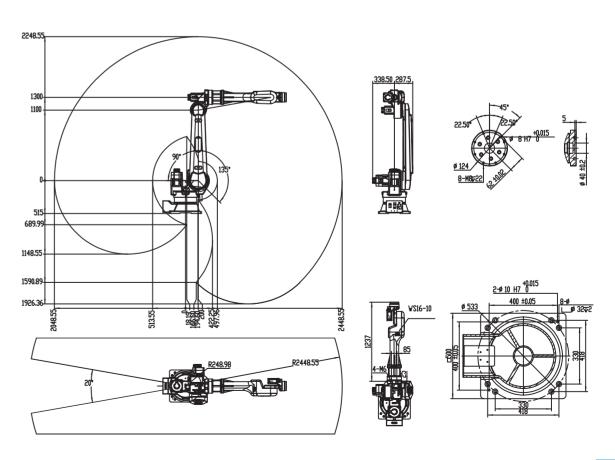






Model	VC-Tk	(B5800
Payload	50kg	
Max Working Radius	2448mm	
DOF	6-axis	
Body Weight	650kg	
Rated Power	7kw	
	J1	127°/s
	J2	105°/s
Max Speed	J3	150°/s
Max Speed	J4	231°/s
	J5	250°/s
	J6	372°/s
	J1	±170°
	J2	-90° ~ 135°
Mario Orangeliana Anna	J3	-185° ~ 90°
Max Operation Area	J4	±200°
	J5	±120°
	J6	±360°
Protective Level	IP54	
Position Repeat Accuracy*	±0.08mm	
Controller	VC-TRC3-C06	
Working Temperature	0~45°C	



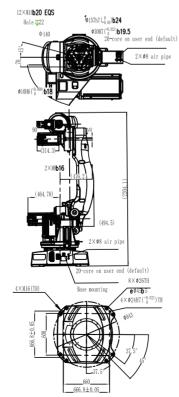


# VC-RRB6700 Payload: 210kg Length: 2700mm

# VC-RRB6600 Payload: 155kg Length: 3200mm

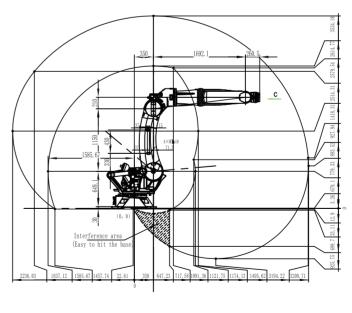
M. I.I.	\/O_DE	D (700
Model	VC-RRB6700	
Payload	210kg	
Max Working Radius	270	0mm
DOF	6-	axis
Body Weight	1300kg	
Rated Power	8.5kw	
	J1	114°/s
	J2	83°/s
	J3	95°/s
Max Speed	J4	180°/s
	J5	165°/s
	J6	219°/s
	J1	±185°
	J2	-50°~ 85°
	J3	-180°~ 70°
Max Operation Area	J4	±360°
	J5	±125°
	J6	±360°
·	J5 J6	IP65
Protective Level	Others	IP54
Position Repeat Accuracy X	±0.1mm	
Controller	VC-TRC3-D06	
Working Temperature	0~45℃	

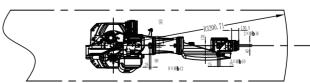
1195. 6 2500. 5.	e e
4XIII 10 10 17 18 18 18 18 18 18 18 18 18 18 18 18 18	
1744. 85 1460. 85 1181. 02 1138. 6 9 347. 00 398. 41 500. 72 664. 37 357. 76 1495. 62 2704. 91 2709. 53	_4
25 3X Nb 10	

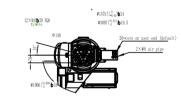


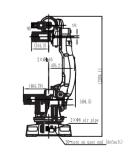
Model	VC-R	RB6600
Payload	155kg	
Max Working Radius	3200mm	
DOF	6-axis	
Body Weight	1320kg	
Rated Power	7	7.5kw
	J1	110°/s
	J2	83°/s
Max Speed	J3	95°/s
Tiux opecu	J4	150°/s
	J5	150°/s
	J6	200°/s
	J1	±185°
	J2	-40°~ 85°
	J3	-180°~ 75°
Max Operation Area	J4	±360°
	J5	±125°
	J6	±360°
Protective Level	J5 J6	IP65
	Others	IP54
Position Repeat Accuracy X		.1mm
Controller	VC-TRC3-D06	
Working Temperature	0~45°C	

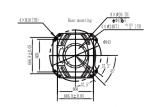






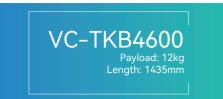






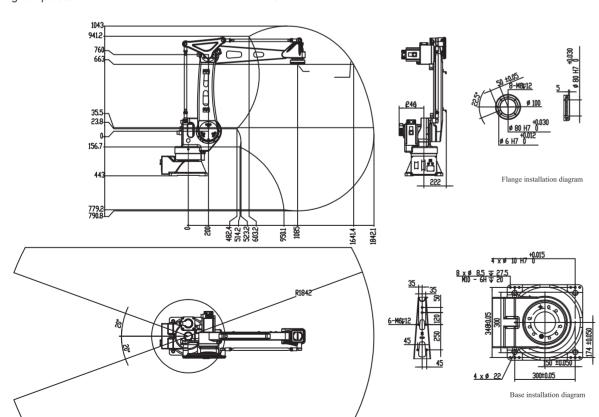


# VC-TKB460 Payload: 30kg Length: 1840mm



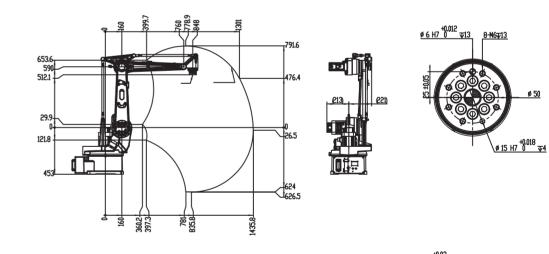
Model	VC-T	VC-TKB460	
Payload	3	30kg	
Max Working Radius	184	1840mm	
DOF	4-	4-axis	
Body Weight	24	0kg	
Rated Power	4.	4.2kw	
	J1	200°/s	
	J2	175°/s	
Max Speed	J3	175°/s	
	J4	360°/s	
	J1	±175°	
	J2	-35° ~ 85°	
Max Operation Area	J3	-90° ~ 70°	
	J4	±360°	
Protective Level	li li	IP54	
Position Repeat Accuracy ※	±0.0	±0.08mm	
Controller	VC-TRC5-B06	VC-TRC5-B06/VC-TRC3-D06	
Working Temperature	0~	0~45°C	

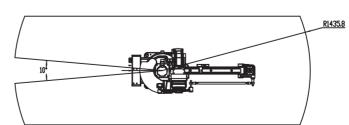




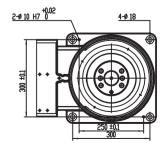
Model	VC-Tk	(B4600	
Payload	12kg		
Max Working Radius		1435mm	
DOF	4-	axis	
Body Weight	17	5kg	
Rated Power	2.5	kw	
	J1	210°/s	
May Chand	J2	205°/s	
Max Speed	J3	185°/s	
	J4	500°/s	
	J1	±175°	
May Operation Area	J2	-35° ~ 85°	
Max Operation Area	J3	-90° ~ 70°	
	J4	±360°	
Protective Level	IP54		
Position Repeat Accuracy*	±0.08mm		
Controller	VC-TRC5-B06	VC-TRC5-B06/VC-TRC3-D06	
Working Temperature	0~4	45℃	







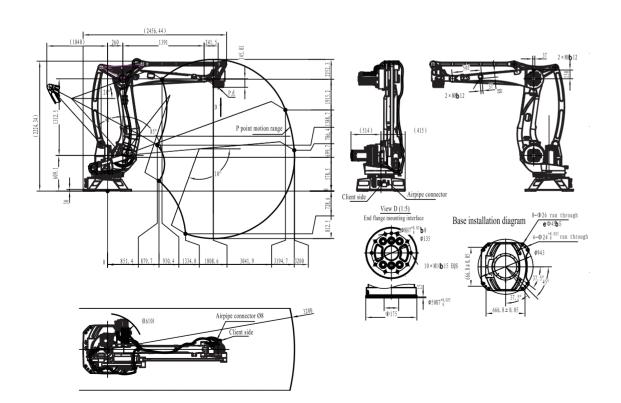




## VC-TKB660 Payload: 180kg Length: 3200mm

Model	VC-TKB660	
Payload	180kg	
Max Working Radius	3200mm	
DOF	4-axis	
Body Weight	1193kg	
Rated Power	5.5kw	
	J1	105° /s
May Spand	J2	83°/s
Max Speed	J3	129.5°/s
	J4	270°/s
	J1	±185°
May Operation Area	J2	-42° ~ 85°
Max Operation Area	J3	-20° ~ 110°
	J4	±360°
Protective Level	IP54/IP65 (4-axis optional)	
Position Repeat Accuracy X	±0.1mm	
Controller	VC-TRC3-C06	
Working Temperature	0~45°C	





## VC-TRP04 Teach Pendant

Model	VC-TRP04-DS	VC-TRP04-QT
Main Chip	REALTEK	ARM
Memory	/	512MBDDR
Capacity	/	4G Flash
OS	/	LINUX
Touch Screen	Resistance-type	Resistance-type
IDE	/	QT5.15
USB	/	USB2.0HOST
Touch Screen Resolution	8"TFT resolution:1024*768	
Key	12 log keys, 4 program control key	s,and 4 customizable function keys
Switch	Emergency stop switch, ena	ble switch, and mode switch
Protection Level	IP54	
Communication	LVDS	Ethernet
Cable Length	5m	10/15/20/30m
Operating Temperature	-30°	~80°
Outer Dimension	290mm*24	0mm*53mm



- High-performance processor: a built-in high-performance processor in the controller, which ensures stable operation and high-speed data transmission to achieve complex multi-axis motion control.
- Various communication interfaces: TRP04 pendant support Ethernet, serial port, CAN bus and more for convenient industrial equipment connection and data interaction.
- Remote monitoring and debugging: Remote access to the TRP04 teach pendant through the Internet for real-time monitoring of the robot's operating status, remote debugging and program updating to improve work efficiency.

## VC-TRC5-B06 Controller

## VC-TRC4-A03 Controller

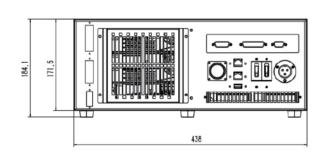
Model	VC-1RC4-AU3
Installation Method	Vertical
Standard IO	18×NPN input,10×RO
Comm Port	Ethernet For TCP/IP, Modbus TCP, Ethernet/IP, and MC communication
	EtherCAT: For external exis expansion
	Modbus-TCP to RS232 or RS485
	USB2.0: For program backup and loading, and export of robot status information
Control Mode	PC programming platform, pendant, remote IO control, remote Modbus control, and API
Protection Level	IP54
Operating Environment	Temp.: 0°C ~40°C; Humidity: 20%~95%RH(30°C) (no condensation)
Dimension	438mmx398mmx185mm
Weight	12kg
Application	VCG030-500,VCG100-700, VCH030-400/500/600,VCH100-800/900/1000, VCH200-1200,VCW030-500/600, VCW060-500/600/700,VC-TKB1010, VC-TRB050,VC-TKB060,VC-TKB070, VC-TKB1210,VC-TKB1100



### Installation Vertical Method Handling: 18×NPN input,10×RO(relay output) Welding: 6×NPN input,10×RO, 2×AO(analog output) Standard IO Ethernet For TCP/IP, Modbus TCP, Ethernet/IP, and MC communication EtherCAT: For external exis expansion Comm Port Modbus-TCP to RS232 or RS485 USB2.0: For program backup and loading, and export of robot status information PC programming platform, pendant, remote IO Control Mode control, remote Modbus control, and API Protection Level IP65 Temp.: 0°C ~40°C; Humidity: 20%~95%RH(30°C) Operating Environment (no condensation) Dimension 850mmx550mmx566mm 76kg Weight VC-TCR300,VC-TKB1400,VC-TKB1440, VC-TKB1600,VC-TKB2030,VC-TKB2670, Application VC-TKB2690,VC-TKB3670,VC-TKB3690, VC-TKB4600,VC-TKB460

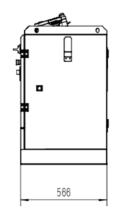


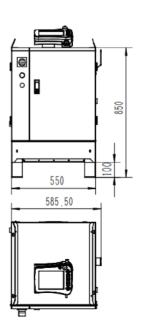
### Controller Dimension

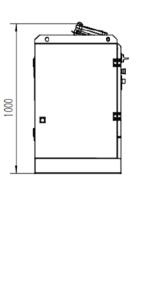




### **Controller Dimension**







## VC-TRC5-G06 Controller

## VC-TRC3-C06 Controller

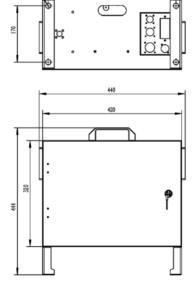
Model	VC-TRC5-G06
Installation Method	Vertical
Standard IO	10×NPN input,14×NPN output
Comm Port	Ethernet For TCP/IP, Modbus TCP, Ethernet/IP, and MC communication
	EtherCAT: For external exis expansion
	Modbus-TCP to RS232 or RS485
	USB2.0: For program backup and loading, and export of robot status information
Control Mode	PC programming platform, pendant, remote IO control, remote Modbus control, and API
Protection Level	IP54
Operating Environment	Temp.: 0°C ~40°C; Humidity: 20%~95%RH(30°C) (no condensation)
Dimension	420mmx235mmx405mm
Weight	14kg
Application	VC-TCR030,VC-TCR050,VC-TCR100, VC-TCR200

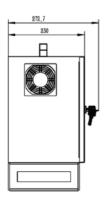


Model	VC-TRC3-C06
Installation Method	Vertical
Standard IO	10×NPN input,14×RO
	Ethernet For TCP/IP, Modbus TCP, Ethernet/IP, and MC communication
	EtherCAT: For external exis expansion
Comm Port	Modbus-TCP to RS232 or RS485
	USB2.0: For program backup and loading, and export of robot status information
Control Mode	PC programming platform, pendant, remote IO control, remote Modbus control, and API
Protection Level	IP54
Operating Environment	Temp.: 0°C ~40°C; Humidity: 20%~95%RH(30°C) (no condensation)
Dimension	1000mmx550mmx606mm
Weight	100kg
Application	VC-TKB5600,VC-TKB5700,VC-TKB5800, VC-TKB660

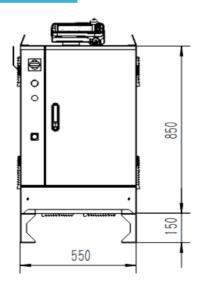


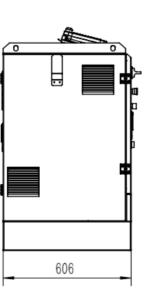
### Controller Dimension





### Controller Dimension





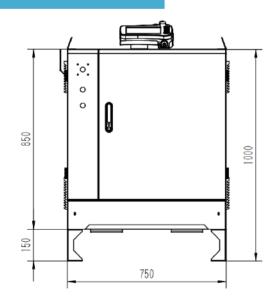
## VC-TRC3-D06 Controller

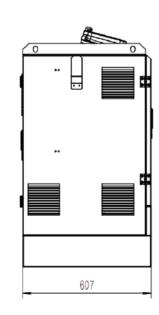
# Application Scenario

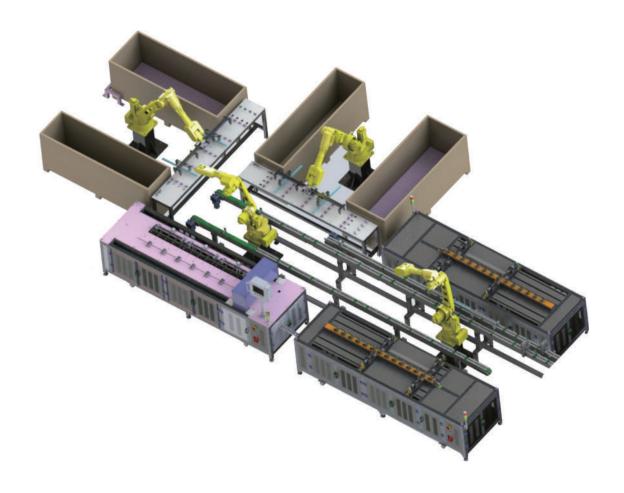
Model	VC-TRC3-D06
Installation Method	Vertical
Standard IO	10×NPN input,14×RO
	Ethernet For TCP/IP, Modbus TCP, Ethernet/IP, and MC communication
	EtherCAT: For external exis expansion
Comm Port	Modbus-TCP to RS232 or RS485
	USB2.0: For program backup and loading, and export of robot status information
Control Mode	PC programming platform, pendant, remote IO control, remote Modbus control, and API
Protection Level	IP54
Operating Environment	Temp.: $0^{\circ}$ C ~40°C; Humidity: 20%~95%RH(30°C) (no condensation)
Dimension	1000mmx750mmx607mm
Weight	140kg
Application	VC-RRB6700,VC-RRB6600,VC-TKB4600, VC-TKB460



### **Controller Dimension**







VEICHI Robotics provides technical services such as robot body and integrated robot platform, which are now widely used across multiple industrial scenarios with successful cases in welding, painting, grinding, teaching, assembling, sorting, machine tool loading and unloading, palleting and handling and more, accumulating unanimous praise from customers. In addition to the traditional industrial scenarios like automotive parts and components, 3C electronics, metal processing, packaging and logistics, university research, etc., Veichi Robotics is also entering into new fields like medical, semiconductor, new energy, photovoltaic, lithium-ion power, and new retail.

## **Application Scenario**

## **Application Scenario**



### Welding

The new generation of innovative welding technology integrates laser trackers, 3D vision systems, and offline trajectory generation, enabling robots to adapt intelligently to complex paths and resist external disturbances.

Automatic welding robots can replace 2-3 welders' workload, ensuring quality while cutting costs. This boosts product qualification rates, shortens iteration cycles, and strengthens customer trust and market competitive-

Automotive parts welding

### Machine Loading and Unloading

Industrial robot loading and unloading applications are characterized by high-precision positioning, high stability, high flexibility, and continuous operation. Equipped with force-assisted devices like torque sensors and vision positioning systems, they can fulfill complex loading and unloading requirements.



Automotive parts robot one-to-four loading and unloading



Linear machine loading and unloading



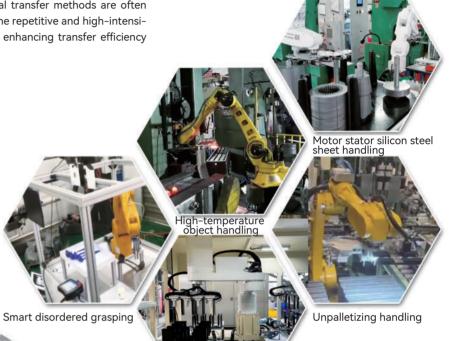
Island one-to-three machine loading and unloading

### **Material Handling**

Palletizing and handling robots are widely used across various industries. Traditional manual material transfer methods are often inefficient, and robots can take over the repetitive and high-intensity tasks, reducing transfer costs and enhancing transfer efficiency for enterprises.



Energy storage cover smart handling



Lithium battery handling



Photovoltaic basket handling

### Gluing

Our proprietary offline programming software is capable of automatically creating robot paths and trajectories for intricate continuous surfaces. Coupled with advanced motion control technology, it provides swift responses, perfectly catering to the demands of precision gluing applications.



Washing machine lid gluing



Control cabinet door panel gluing

## **Application Scenario**

# Collaborative Application Scenarios

### **Polishing**

Polishing applications are characterized by difficult programming, high-frequency vibrations, and constant torque output. We have independently developed offline programming software and developed a force control process package to control the constant pressure during the trajectory operation and customized mechanical structures to solve the difficulties in polishing applications.



Deburring of castings



Polishing

### **Screw Fastening**

Equipped with a screw fastening process package, it features torque feedback, multi-stage torque control, and detection functions for abnormal situations such as missed screws, floating, and slipping teeth, meeting customer needs.



TKB060 Vision-guided screw fastening



TKB070 screw fastening



C-side of a laptop screw fastening



Household appliances screw fastening

### **Collaborative Robots**

Collaborative robots represent the next generation of industrial automation, engineered to collaborate seamlessly with human workers. Our company is dedicated to advancing the field of collaborative robotics through focused research, development, and implementation. We are committed to delivering top-tier solutions for welding automation, aiding in the modernization and transformation of the manufacturing sector.

Leveraging our team of expert engineers, we are equipped to offer comprehensive technical solutions tailored to our clients' needs. We are well-prepared to swiftly deliver practical automation solutions that align with the principles of Industry 4.0, ensuring that our customers can benefit from the latest advancements in smart manufacturing.



Automatic coffee latte art

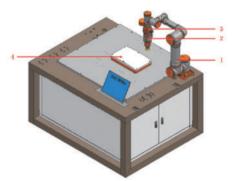


Automatic labeling machine

Light bulb picking



Household appliance screw fastening



Surface polishing



Laser navigation composite robot



### Partners

## Other Application Scenarios



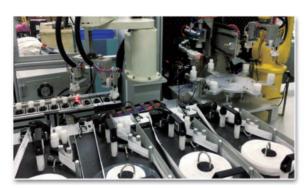
Emergency Handling in the 3C Industry Intelligent Data Center



Automobile Front Beam Press **Equipment Production Line** 



Unmanned Factory of a Top 500 Global **Environmental Protection Enterprise** 



LED Assembly in the Lighting Industry



Laser Cutting



**Educational Demonstration Workstation** 

